Dirac's Conjecture about Constraints

Qi Zhi¹

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Combining Costa's theory with our algorithm, we recalculate Cawly's counterexample which contains χ^n -type constraints. The result shows that Dirac's conjecture holds true whether or not there are γ ⁿ-type constraints.

1. INTRODUCTION

According to Dirac's conjecture (Dirac, 1964), all first-class constraints should be generators of gauge transformations. Costa *et al.* (1985) and Castellani (1982) proved this and derived the gauge generators of constrained systems, respectively. Moreover, Costa *et al.* (1985) calculated two examples: electrodynamics and the Christ-Lee model, and pointed out that if a quantity $f(q, p)$ is first class, it must be gauge invariant and

$$
\dot{f}(q,p) \approx [f, H_T] \approx [f, H_E] \tag{1}
$$

which explicitly shows that H_T and H_E generate the same time evolution for the canonical gauge-invariant functions $f(q, p)$, i.e., H_T and H_F are physically equivalent. If a quantity $f(q, p)$ is a gauge-dependent variable, H_T and H_F generate different equations of motion. For a gauge-dependent variable, it makes no sense whatsoever to compare f_T constructed in the H_T formalism with f_E constructed in the H_E formalism, because of the existence of "formalism-dependent" realizations.

In Section 2, combining the theory of Costa *et al.* (1985) with our algorithm, we recalculate Cawly's counterexample (Cawly, 1979), which was excluded by Costa *et al.* (1985) and Castellani (1982). Some final remarks and conclusions are contained in Section 3.

¹Department of Biomedical Engineering, Capital Institute of Medicine, Beijing 100054, China.

2. RECALCULATION OF CAWLY'S COUNTEREXAMPLE

In Cawly's (1979) famous counterexample

$$
L = \dot{X}\dot{Z} + 1/2YZ^2 \tag{2}
$$

which yields primary first-class constraints

$$
\phi = P_y \approx 0 \tag{3}
$$

the total Hamiltonian is

$$
H_T = P_z P_x - 1/2 Y Z^2 + \xi P_y \tag{4}
$$

On the basis of our previous paper (Qi, 1990), the secondary first-class constraints are

$$
\chi_1 = Z^2 \approx 0 \tag{5a}
$$

$$
\chi_2 = Z P_x \approx 0 \tag{5b}
$$

$$
\chi_3 = P_x^2 \approx 0 \tag{5c}
$$

and within the H_T formalism the gauge generator g is

$$
g = \ddot{\varepsilon}_{(t)} P_{y} + \ddot{\varepsilon}_{(t)} Z^{2} + \dot{\varepsilon}_{(t)} Z P_{x} + \varepsilon_{(t)} P_{x}^{2}
$$
 (6)

Thus, the gauge transformations are

$$
\delta X = \dot{\varepsilon} Z \tag{7a}
$$

$$
\delta Y = \ddot{\varepsilon} \tag{7b}
$$

$$
\delta Z = 0 \tag{7c}
$$

$$
\delta P_x = 0 \tag{7d}
$$

$$
\delta P_y = 0 \tag{7e}
$$

$$
\delta P_z = -2\ddot{\varepsilon}Z - \dot{\varepsilon}P_x \tag{7f}
$$

$$
\delta \xi = \ddot{\epsilon} \tag{7g}
$$

From (4), the equations of motion are

$$
\dot{X} \approx P_z \tag{8a}
$$

$$
\dot{Y} \approx \xi \tag{8b}
$$

$$
\dot{Z} \approx P_{x} \tag{8c}
$$

$$
\dot{P}_x \approx 0 \tag{8d}
$$

$$
\dot{P}_y \approx 1/2Z^2 \approx 0 \tag{8e}
$$

$$
\dot{P}_z \approx YZ \tag{8f}
$$

which are invariant under (7).

Within the H_E formalism, the extended Hamiltonian is

$$
H_E = P_z P_x + \xi_1 P_y + \xi_2 Z^2 + \xi_3 Z P_x + \xi_4 P_x^2 \tag{9}
$$

and the gauge generator is

$$
G = \tau_1 P_y + \tau_2 Z^2 + \tau_3 Z P_x + \tau_4 P_x^2 \tag{10}
$$

and the gauge transformations are

$$
\delta X = \tau_3 Z + 2\tau_4 P_x \tag{11a}
$$

$$
\delta Y = \tau_1 \tag{11b}
$$

$$
\delta Z = 0 \tag{11c}
$$

$$
\delta P_x = 0 \tag{11d}
$$

$$
\delta P_{y} = 0 \tag{11e}
$$

$$
\delta P_z = -2\tau_2 Z - \tau_3 P_x \tag{11f}
$$

From (9), the equations of motion are

$$
\dot{X} \approx P_z + \xi_3 Z + 2\xi_4 P_x \tag{12a}
$$

$$
\dot{Y} \approx \xi_1 \tag{12b}
$$

$$
\dot{Z} \approx P_x \tag{12c}
$$

$$
\dot{P}_x \approx 0 \tag{12d}
$$

$$
\dot{P}_y \approx 0 \tag{12e}
$$

$$
\dot{P}_z \approx -2\xi_2 Z - \xi_3 P_x \tag{12f}
$$

which are invariant under (11), provided the Lagrange multipliers ξ_1 , ξ_2 , ξ_3 , and ξ_4 transform, respectively, as (Costa *et al.*, 1985)

$$
\delta \xi_1 = \dot{\tau}_1 \tag{13a}
$$

$$
\delta \xi_2 = \dot{\tau}_2 + \frac{1}{2} \tau_1 \tag{13b}
$$

$$
\delta \xi_3 = \dot{\tau}_3 + 2\tau_2 \tag{13c}
$$

$$
\delta \xi_4 = \dot{\tau}_4 + \tau_3 \tag{13d}
$$

Analyzing (7) and (11), we find that X, P_z , and Y are gauge-dependent variables; and the basic canonical gauge-invariant functions $f(q, p)$ are Z, P_x , and P_y . So both sets of equations (8) and (12) yield the same time evolution for the gauge-invariant functions $f(q, p)$ as seen from

$$
\dot{Z} \approx P_{x} \tag{14a}
$$

$$
\dot{P}_x \approx 0 \tag{14b}
$$

$$
\dot{P}_y \approx 0 \tag{14c}
$$

This result agrees with that of Costa *et al.* (1985), but the system contains χ^n -type constraints.

3. CONCLUSION

Reexamining Costa's and Castellani's proof, we find that it is not necessary to reject χ^n -type constraints. If we do not linearize the constraints like Cawly (1979) and others. Costa's theory can contain χ^n -type constraints. This also proves indirectly the correctness of the algorithm proposed in our previous paper (Qi, 1990). We conclude the Dirac's conjecture holds true whether or not there are γ ⁿ-type constraints.

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